

We touch your **electricity** everyday!

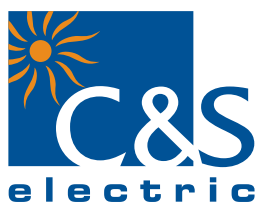
CSENEX-I 100/101

Intelligent Measuring and Protection Device

CSENEX
CSENEX
CSENEX
CSENEX
Series



Catalog



CE

PMD Division

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1) Introduction

CSENEX Series offers a compact Multi-functional Over-current protection solution for Feeder, Generator, Motor & Transformer segment.

CSENEX-I Family of protective relays are numeric relays that provides multi protection and monitoring with reliable and fast protection solution in a single unit.

In this family of CSENEX series, the CSENEX-I is an feeder protection solution which has fast, sensitive and secure protection for feeder internal & external faults.

CSENEX-I offers different model based features to cover the wide range of user.

2) Features

- ❖ 1A & 5A rated CT input (site selectable).
- ❖ Three phase time over-current protection.
- ❖ Draw out with self CT shorting (Depend upon the Model).
- ❖ Three phase instantaneous protection.
- ❖ Earth time over-current and earth instantaneous over current.
- ❖ Circuit breaker failure detection.
- ❖ Trip circuit supervision.
- ❖ Event recorder.
- ❖ Fault recorder.
- ❖ Trip Counter.
- ❖ DI/DO programmable matrix.
- ❖ Communication (Local & Remote).

3) Application

The CSENEX-I relays have been designed for controlling, protecting and monitoring industrial, utility distribution networks and substations. They can also be used as part of a protection scheme for feeders, transformers and generators.

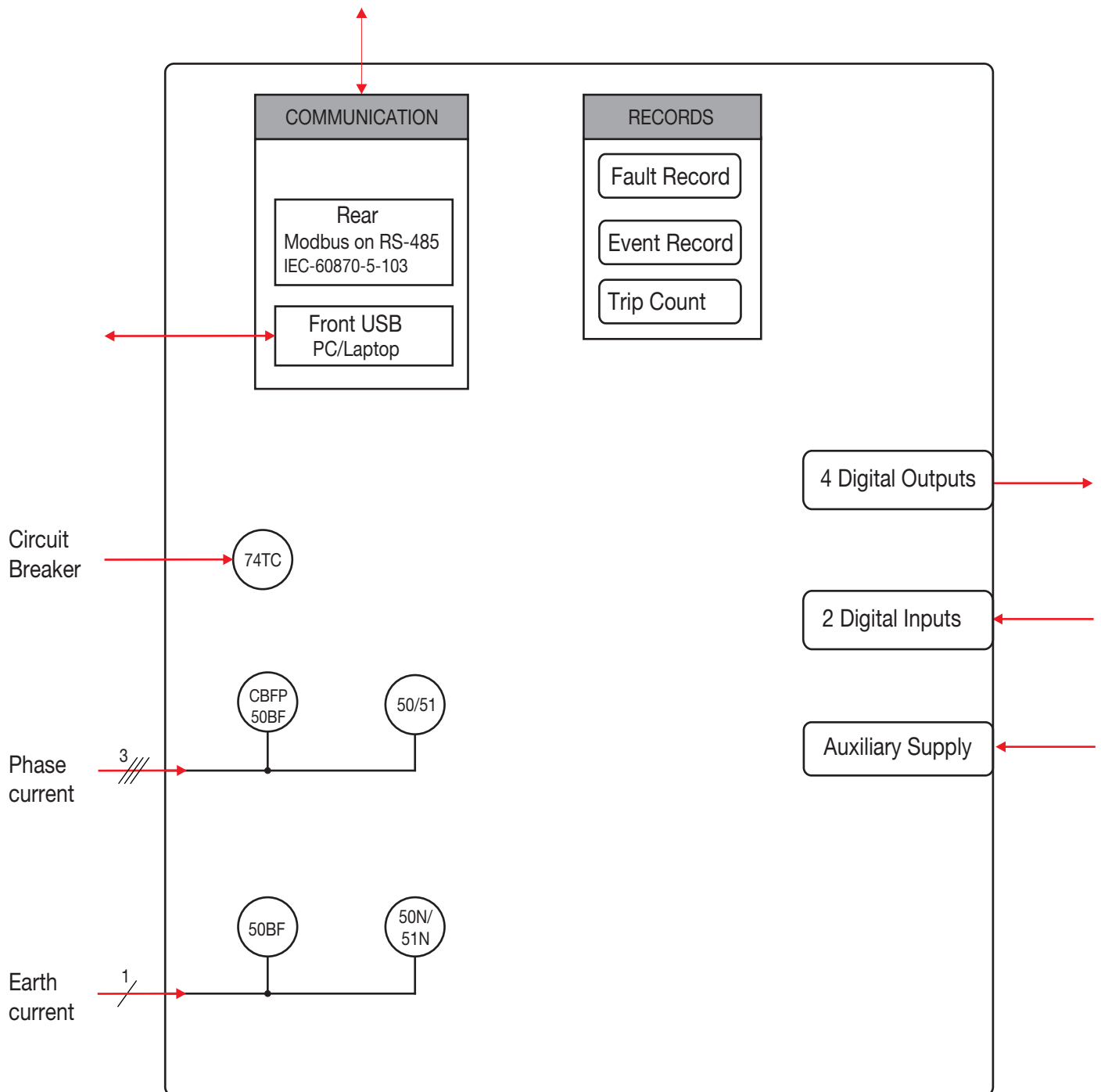
4) Hardware

- ❖ Micro controller based numeric design
- ❖ Measures true RMS with DFT filter
- ❖ 4 Current analog inputs
- ❖ Max. 2 digital inputs
- ❖ Max. 4 digital outputs
- ❖ Alpha numeric (12 x 2) LCD
- ❖ 5 Push button on the front for MMI
- ❖ RS-485 & USB communication

5) Protection Features

- ❖ Three phase time over current protection (51)
- ❖ Three phase instantaneous protection (50)
- ❖ Earth time over-current (51N)
- ❖ Earth instantaneous over-current (50N)
- ❖ Circuit breaker failure protection (50BF)
- ❖ Trip Circuit Supervision (74TC)
- ❖ Cold Load Pickup (62CLD)
- ❖ Harmonic Blocking (50H)

6) Functional Diagram



(Figure 1)

Protection Function

Three Phase Over-current Protection (50/51)

The independent two stages are available for phase fault protection. For I> the user may independently select definite time delay or inverse time delay with different type of curves. The second Hi-Set stage can be configured with definite time only.

Earth Fault Protection (50N/51N)

The independent two stages are available for earth fault protection. For first stage (Ie>) the user can select definite time delay or inverse time delay with different type of curves. The second Hi-Set stage can be configured with definite time only.

Trip Circuit Supervision (74TC)*

This feature continuously supervises trip circuit of both pre closing and post closing conditions in circuit breaker. It detects tripping mechanism failure like circuit breakage contact degeneration in wires, contacts and coils.

Circuit Breaker Failure Protection (50 BF)

The CB Failure Protection is based on supervision of phase and earth currents after tripping events. The test criterion is whether all phase currents have dropped to less than 5% of I_n within tCBFP. If one or more of the phase currents have not dropped to specified current within this time, CB failure is detected and the assigned output relay is activated.

Harmonic based Protection Blocking

To avoid any nuisance tripping, CSENEX-I provides harmonic detection & protection blocking feature. Relay will hold the tripping for a set time, If harmonic is present with protection pickup. Blocking time & harmonic selection is configurable in the relay.

Note: Harmonics is detected based on presence for at least 2 cycles.

Protection blocking due to harmonics is active, when percentage of harmonics present is more than 25% of fundamental current.

Cold Load Pickup

This function aims to avoid non-desired trips in the following situation: after being the line de-energized for a period of time and re-energized later, the load exceed the protection setting without the presence of a fault. This may be due to the fact that the “off” period of all the loads (furnaces, heaters, coolers etc.) is elapse and they are all connected at the same time, producing a strong inrush current in the line, but which can be supported within certain time. This phenomenon can occur not only at the moment of the breaker manual closing, after having remained open for a certain time, but also with the breaker permanently closed due to the operation of another upstream breaker.

What the function does is detecting when those conditions are given and changing the tripping settings during a programmable time.

The function is activated when the current in the 3 phases is below 0.08A, then the programmed time starts to run to determine that the load is “cold” (this time can be 0, what means that any circuit breaker opening could lead to the cold load situation). Once that time has expired and the current has not exceed again 0.15A, the protection usual setting values are replaced by the cold load pickup ones. When any of the phase current exceed 0.15A a counter with programmable time starts, during which the setting are the cold load pickup ones. When expiring this time, the settings are again the usual ones.

7) Fault Records

CSENEX-I records last 10 faults in its non volatile memory with it's time stamp. Each record has the following information:

Fault Format

[F] IL1 : 00.00A
 [F] IL2 : 00.00A
 [F] IL3 : 00.00A
 [F] Ie : 00.00A
 HOUR MIN : HH:MM
 SEC mSEC : Sec:mSec
 F-TYPE : FAULT TYPE

Where

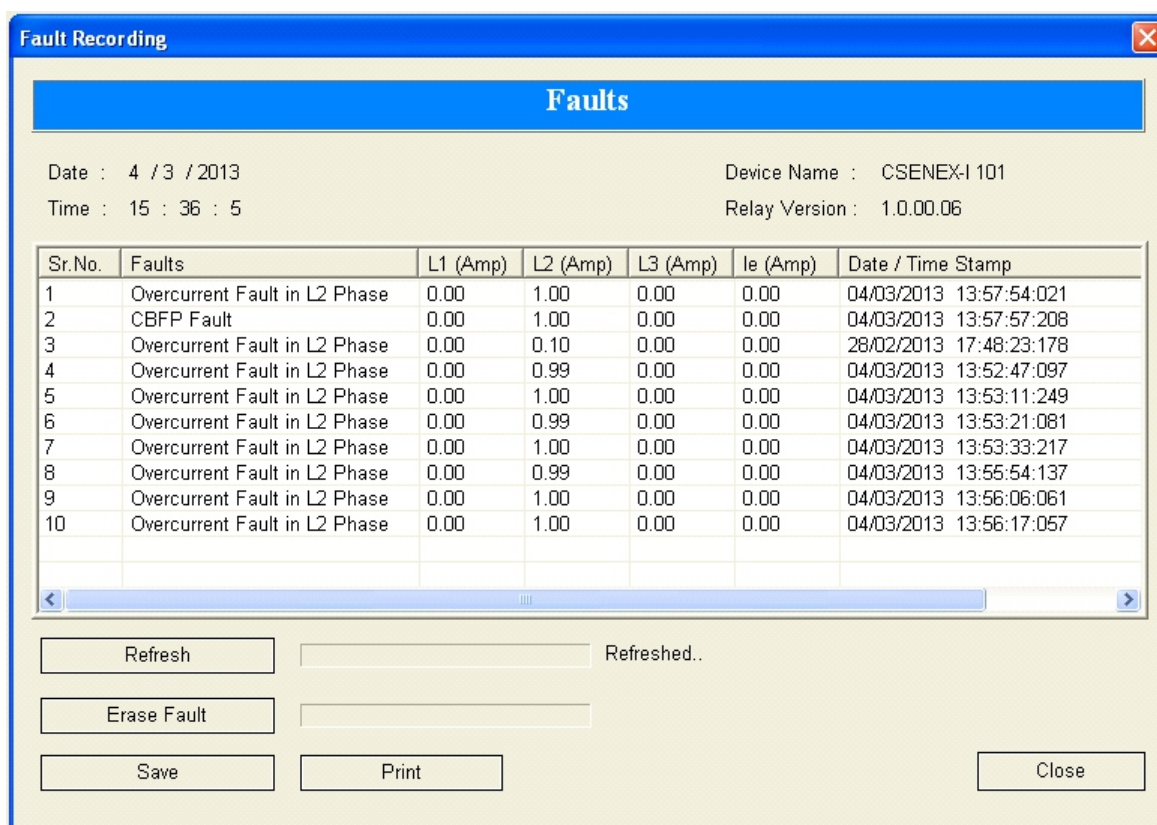
[F]ILx] Magnitude of phase current's.

[F]Ie Magnitude earth fault current's

F-Type Origin of fault (over current, negative phase sequence, etc.) (See Figure 2)

whenever the available memory space is exhausted the new fault automatically over writes the oldest fault. When the relay trips the description of fault in the feeder will appears on the LCD screen automatically and by pressing 'i' key one can easily get all the detailed information of that fault.

The user can view the fault record either via the front USB interface software or remotely via the RS-485 communication.(See figure-2)



| Sr.No. | Faults | L1 (Amp) | L2 (Amp) | L3 (Amp) | Ie (Amp) | Date / Time Stamp |
|--------|-------------------------------|----------|----------|----------|----------|-------------------------|
| 1 | Overcurrent Fault in L2 Phase | 0.00 | 1.00 | 0.00 | 0.00 | 04/03/2013 13:57:54:021 |
| 2 | CBFP Fault | 0.00 | 1.00 | 0.00 | 0.00 | 04/03/2013 13:57:57:208 |
| 3 | Overcurrent Fault in L2 Phase | 0.00 | 0.10 | 0.00 | 0.00 | 28/02/2013 17:48:23:178 |
| 4 | Overcurrent Fault in L2 Phase | 0.00 | 0.99 | 0.00 | 0.00 | 04/03/2013 13:52:47:097 |
| 5 | Overcurrent Fault in L2 Phase | 0.00 | 1.00 | 0.00 | 0.00 | 04/03/2013 13:53:11:249 |
| 6 | Overcurrent Fault in L2 Phase | 0.00 | 0.99 | 0.00 | 0.00 | 04/03/2013 13:53:21:081 |
| 7 | Overcurrent Fault in L2 Phase | 0.00 | 1.00 | 0.00 | 0.00 | 04/03/2013 13:53:33:217 |
| 8 | Overcurrent Fault in L2 Phase | 0.00 | 0.99 | 0.00 | 0.00 | 04/03/2013 13:55:54:137 |
| 9 | Overcurrent Fault in L2 Phase | 0.00 | 1.00 | 0.00 | 0.00 | 04/03/2013 13:56:06:061 |
| 10 | Overcurrent Fault in L2 Phase | 0.00 | 1.00 | 0.00 | 0.00 | 04/03/2013 13:56:17:057 |

(Figure 2) (Fault Data Recording on PC software)

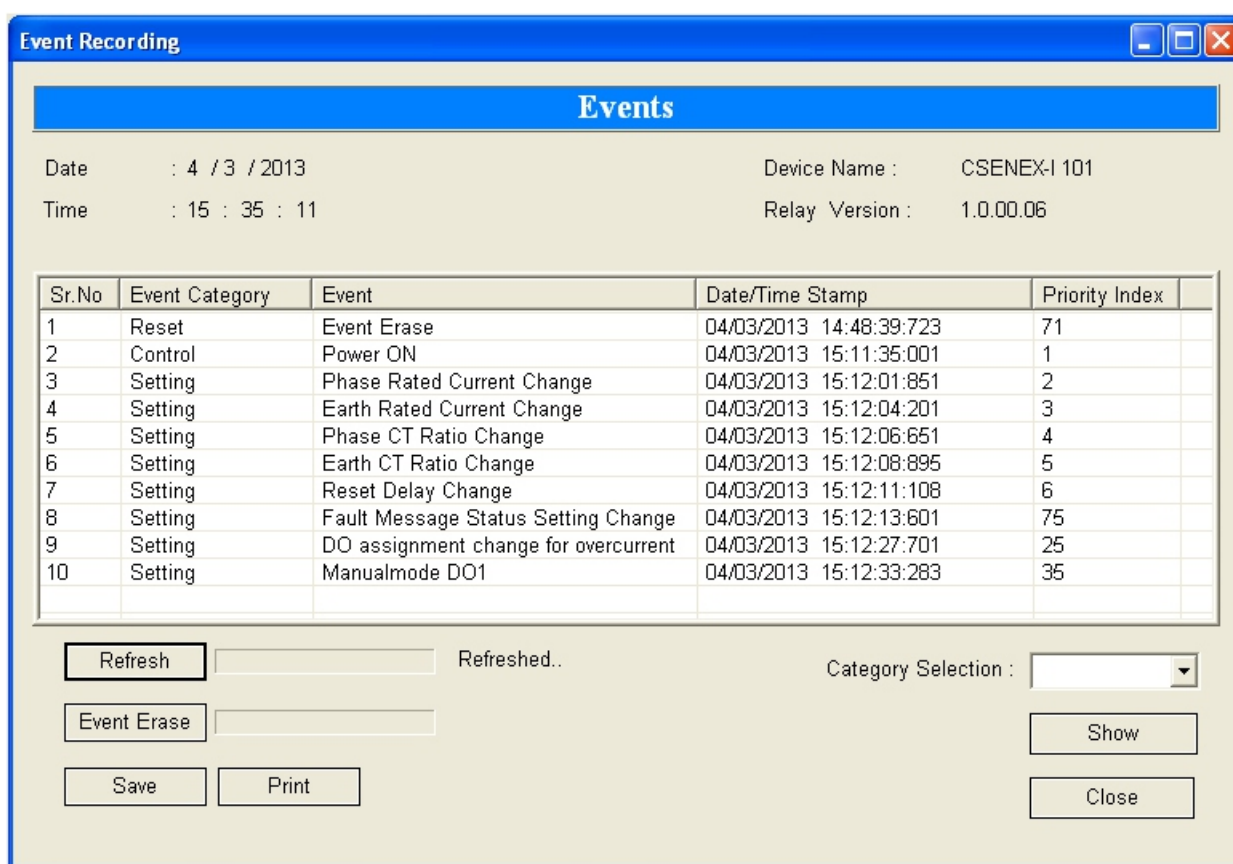
8) Event Records

The unit stores in non volatile memory the last 16 events. When the available memory space is exhausted, the new event automatically overwrites the oldest event which can be retrieved from a PC, with the following format:

| | | |
|----------|---|--------------|
| EVENT | : | EVENT NUMBER |
| HOUR | : | HH:MM |
| SEC mSEC | : | SEC:mSEC |
| DATE | : | DD/MM/YY |

The user can view event records via the front USB interface software (See Figure 3)

*Description of event number available in event list or in front end software



| Sr.No | Event Category | Event | Date/Time Stamp | Priority Index |
|-------|----------------|--------------------------------------|-------------------------|----------------|
| 1 | Reset | Event Erase | 04/03/2013 14:48:39.723 | 71 |
| 2 | Control | Power ON | 04/03/2013 15:11:35.001 | 1 |
| 3 | Setting | Phase Rated Current Change | 04/03/2013 15:12:01.851 | 2 |
| 4 | Setting | Earth Rated Current Change | 04/03/2013 15:12:04.201 | 3 |
| 5 | Setting | Phase CT Ratio Change | 04/03/2013 15:12:06.651 | 4 |
| 6 | Setting | Earth CT Ratio Change | 04/03/2013 15:12:08.895 | 5 |
| 7 | Setting | Reset Delay Change | 04/03/2013 15:12:11.108 | 6 |
| 8 | Setting | Fault Message Status Setting Change | 04/03/2013 15:12:13.601 | 75 |
| 9 | Setting | DO assignment change for overcurrent | 04/03/2013 15:12:27.701 | 25 |
| 10 | Setting | Manualmode DO1 | 04/03/2013 15:12:33.283 | 35 |

(Figure 3) (Event Data Recording on PC Software)

Output Contacts

| | | |
|------------------------------|---|----------------------------------------------------------|
| No. of digital outputs | : | 4 (DO1, DO2, DO3, DO4) [2 Change Over, 2 Normal Open] |
| Type of outputs | : | Relay |
| Programmable (DO Assignment) | : | Yes |
| Relay reset type | : | Programmable (Auto/Manual) |






Input Contacts

| | | |
|------------------------------|---|--------------|
| No of digital inputs | : | 2 (DI1, DI2) |
| Programmable (DI Assignment) | : | Programmable |

9) Human Machine Interface

It comprises of bright LCD display

- ❖ Four push switches for setting values of normal tripping characteristics and other operations for local access.
- ❖ One 'RESET' push switch.
- ❖ One push switch for the functions assigned in the 'HMI'.
- ❖ Sixteen LEDs for pickup or tripping on fault and event in any phase.

| Keys | Manual Key |
|-----------------------------------------------------------------------------------|-------------------------------------------------------------------------------|
|  | is used as intelligent key to see the details of last fault and Relay status. |
|  | is used as a "ENTER" key. |
|  | is used to manual reset (after pressing for 2 sec) |
|  | is used to scroll in downward direction. |
|  | is used to scroll in upward direction. |



(Figure 4) (HMI)

10) Communication (Local & Remote)

The unit has:

- ❖ 1 Front USB port for direct connection to a PC
- ❖ 1 Rear RS-485 communication port

10.1) Rear Communication * (Model dependent)

The protocol for the rear port is MODBUS-RTU, IEC-60870-5-103.

10.2) Front Communication

The entire setting, Fault & Event are available on 'A' type USB (female) interface with CSE LIVELINK with saving & printing option. This unit also has Front-end Live Link simulation support for testing of relay even without any three phase injection source.

11) Setting Ranges

Over Current & Earth Protection

| S. No | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|--------------------------------------------|---------|---------------|---------|-----------------------------------------------|-----------------|
| | | | Min. | Max. | | |
| 1 | Phase over-current characteristics | PCh | | | DEFT/EINV/VINV /LINV/NINV1.3/ NINV3.0/NINV0.6 | DEFT |
| 2 | Earth over-current Characteristics | ECh | | | DEFT/EINV/VINV /LINV/NINV1.3/ NINV3.0/NINV0.6 | DEFT |
| 3 | Phase over-current low set pickup setting | I> | 0.05xIp | 4.0xIp | 0.01xIp | EXIT |
| | Phase over-current definite timing | t> | 0.1 Sec | 150 Sec | 0.01Sec | 0.10 Sec |
| | Phase over-current inverse timing | ti> | 0.01 | 1.50 | 0.005 | 0.05 |
| 4 | Phase over-current hi-set pickup setting | I>> | 0.5xIp | 30xIp | 0.1xIp | EXIT |
| | Phase over-current hi-set definite timing | t>> | 0.03 Sec | 20 Sec | 0.01Sec | 0.10 Sec |
| 5 | Earth over-current low set pickup setting | Ie> | 0.05xIn | 2.5xIn | 0.01xIn | EXIT |
| | Earth over-current low set definite timing | te> | 0.03 Sec | 150 Sec | 0.01Sec | 0.10 Sec |
| | Earth over-current low set inverse timing | tie> | 0.01 | 1.50 | 0.005 | 0.05 |
| 6 | Earth over-current hi-set pickup setting | Ie>> | 0.5xIn | 8xIn | 0.05xIn | EXIT |
| | Earth over-current hi-set definite timing | te>> | 0.03 Sec | 20 Sec | 0.01 Sec | 0.10 Sec |

Very Inverse
$$t = \frac{13.5}{(I/I_s) - 1} t_i [s]$$

Extremely Inverse
$$t = \frac{80}{(I/I_s)^2 - 1} t_i [s]$$

Long time Inverse
$$t = \frac{120}{(I/I_s) - 1} t_i [s]$$

Normal Inverse 3.0/1.3/0.6
$$t = \frac{0.14/0.061/0.028}{(I/I_s)^{0.02} - 1} t_i [s]$$

Where t = Tripping time t_i = Time multiplier
 I = Fault current I_s = Setting value of current

For Current Range 0.2 to 20xIn:

Trip timing Accuracy : VINV / NINV 3.0 / 1.3 / DEFT : +5% OR +30mSec (whichever is higher)
 EINV / NINV 0.6 / LINV : +7.5% OR +30mSec (whichever is higher)

For Current Range 0.05 to 0.2xIn:

Trip timing Accuracy : VINV / NINV 3.0 / 1.3 / DEFT : +20% OR +40mSec (whichever is higher)
 EINV / NINV 0.6 / LINV : +20% OR +40mSec (whichever is higher)

Note = * Availability as per model selection.

Trip Circuit Supervision Protection*

| S.No. | Parameter | Display | Setting Ranges | | Step Size | Default |
|-------|-----------|---------|----------------|-----|-----------|---------|
| | | | Min | Max | | |
| 1 | TCS | t_TCS | 0.03 | 2 | 0.01 | EXIT |

Circuit Breaker Failure Protection

| S.No. | Parameter | Display | Setting Ranges | | Step Size | Default |
|-------|-----------|---------|----------------|-----|-----------|---------|
| | | | Min | Max | | |
| 1 | CBFP | t_CBFP | 0.03 | 2 | 0.01 | EXIT |

DO Reset

| S.No. | Display | Setting Ranges | Default |
|-------|---------|----------------|---------|
| 1 | DO-1 | Auto / Manual | Auto |
| 2 | DO-2 | Auto / Manual | Auto |
| 3 | DO-3 | Auto / Manual | Auto |
| 4 | DO-4 | Auto / Manual | Auto |

DI Assignment *

| S.No. | Parameter | Display | Min | Max | Step Size | Default |
|-------|-----------------------|----------|-----|------|-----------|---------|
| 1 | Circuit Breaker Close | CB close | DI1 | Exit | ---- | ---- |
| 2 | Circuit Breaker Open | CB open | DI1 | Exit | ---- | ---- |

Erase Record

| S.No. | Parameter | Display | Min | Max | Step Size | Default |
|-------|--------------------|---------|-----|-----|-----------|---------|
| 1 | Event Erase | Events | NO | YES | ---- | NO |
| 2 | Fault Erase | Faults | NO | YES | ---- | NO |
| 3 | Trip Counter Erase | TRP_CNT | NO | YES | ---- | NO |

Harmonic Blocking *

| S.No. | Parameter | Display | Min | Max | Step | Default |
|-------|---------------------|---------|------|-------|-------|---------|
| 1 | Phase harmonic | Ph_Har | NO | YES | ----- | NO |
| 2 | Earth Harmonic | ET_Har | NO | YES | ----- | NO |
| 3 | Phase blocking time | t_Ph | 0.10 | 20.00 | ----- | 0.10 |
| 4 | Earth blocking time | t_Et | 0.10 | 20.00 | ----- | 0.10 |

DO Assignment

| S.No | Parameter | Display | Min | Max | Default |
|------|------------------------------------|---------|-----|------|---------|
| 1 | Phase over-current low set | I> | 1 | 1234 | ---- |
| 2 | Phase over-current hi-set | I>> | 1 | 1234 | ---- |
| 3 | Earth over-current low set | E> | 1 | 1234 | ---- |
| 4 | Earth over-current hi-set | E>> | 1 | 1234 | ---- |
| 5 | Self supervision | Slfsup | 1 | 1234 | ---- |
| 6 | Trip Circuit protection | TCS | 1 | 1234 | ---- |
| 7 | Circuit breaker failure protection | CBFP | 1 | 1234 | ---- |

Note = * Availability as per model selection.

Cold Load Pickup Setting

| S.No | Parameter | Display | Min | Max |
|------|---------------------------------|---------|----------|----------|
| 1 | Cold Load Pickup enable | CLP PKP | NO | YES |
| 2 | Cold Load Short Circuit Setting | I>> | 0.50 xlp | 30.0 xlp |
| 3 | Cold Load Short Circuit Time | t>> | 0.03 s | 20.00 s |
| 4 | Cold Load Earth Hi-set Setting | Ie>> | 0.50 xln | 8.0 xln |
| 5 | Cold Load Earth Hi-set Time | te>> | 0.03 s | 20.00 s |
| 6 | Cold Load Time | tcl | 0.00 s | 100.00 s |
| 7 | Cold Load Pickup Time | tac | 0.00 s | 100.00 s |

Common Setting: (These are the settings common for all protections)

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|-----------------------|----------------|---------------|--------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1. | Rated phase current * | I _p | 1 A | 5 A | ----- | 1 A |
| 2. | Rated earth current * | I _n | 1 A | 5 A | ----- | 1 A |
| 3. | Phase CT ratio | P-CTR | 1 | 9999 | 1 | 1 |
| 4. | Earth CT ratio | E-CTR | 1 | 9999 | 1 | 1 |
| 5. | Reset Delay | Rstdl | 0 Sec | 20 Sec | 0.1sec | 0 |
| 6. | Fault Message Status | F-Stats | NO | YES | ----- | NO |

Rear port RS-485/RS-232 Communication setting

(*Availability as per model selection)

| | |
|------------------------------------|---------------------------------|
| Protocol | MODBUS RTU, IEC-60870-5-103 |
| Baud rate selection (programmable) | 9600/19200/38400 bps |
| Parity selection (programmable) | Even / Odd / None |
| Stop bit | 1 Bit |
| Data bit | 8 Bit data |
| Remote Address (programmable) | (1 to 247) |
| Cable required for interface | Two wire twisted shielded cable |

USB Communication

| | |
|------------------------------|---------------------------------------------------------|
| Protocol | CSE proprietary protocol: available with front software |
| Baud rate | 19200 bps |
| Cable required for interface | USB cable type (A to A) |

Auxiliary Supply

| | | |
|--------------------------------|----------------------|----------------------------|
| Auxiliary Voltage Range | For 'L' Model | 18V-60V DC |
| | For 'W1' Model | 18V-150V DC |
| | For 'H' Model | 85V-280V AC / 110V-300V DC |
| Supply Range for Digital Input | For 'L & H' Model | 24V above AC/DC |
| Power Consumption | Quiescent approx. 3W | Operating approx. <7W |

Measurement Accuracy

| Quantity | Range | Frequency Range | Accuracy |
|----------|--------------|-----------------|----------|
| Current | 1.0 - 30 xlp | 50 Hz | +2% |

12) Technical Data

Measuring Input

| | |
|----------------------------------------------------|------------------------------------|
| Rated Data | Rated current I_p : 1A or 5A |
| | Rated frequency F_n : 50 Hz/60Hz |
| Drop out to Pickup Ratio | >96% |
| Power consumption in current circuit | At $I_p=1A$ 0.2 VA |
| | At $I_p=5A$ 0.4 VA |
| Thermal withstand capability in current circuit | Dynamic current withstand |
| | (half wave): 250 x I_p |
| | for 1 Sec : 100 x I_p |
| | for 10 Sec : 30 x I_p |
| | continuously : 4 x I_p |

13) Type Test

| | |
|--------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------|
| DESIGN STANDARD | |
| Specified ambient service temp. range | VDE 04355 part 303, IEC 255-4, BS 142 |
| For storage | 40°C to + 85°C |
| For operation | -20°C to 70°C |
| Environmental protection class 'F' as per DIN 40040 and per DIN IEC 68, part 2.3 | relative humidity 95% at 40 deg C for 56 days. |
| Isolation test voltage, inputs and outputs between themselves and to the relay frame as per VDE 0435, part 303 | 2.5 KV (eff.) / 50 Hz, 1 min. |
| Impulse test voltage, inputs and outputs between themselves and to the relay frame as per VDE IEC 0435, part 303 | 5 KV, 1.2/50ms, 0.5J |
| High frequency interference test voltage, inputs and outputs between themselves and to the relay frame as per DIN IEC 255, part 22-1 | 2.5 KV/1MHz |
| Electrical fast transient (burst) test as per DIN VDE 0843 part 4 | 4KV / 2.5 kHz, 15ms |
| Radio interference suppression test as per DIN VDE 57 871 | Limit value class 'B' |
| Electrostatic discharge (ESD) test as per DIN VDE 0843 part 2 | 8 KV |
| Radiated electromagnetic field test as per VDE 0843 part2 | 10 V/m |

14) Mechanical Test

| | |
|------------------------|--------------------------------------|
| Shock | As per DIN IEC 41 B (CO) 38: class 1 |
| Vibration | As per DIN IEC 41 B (CO) 35: class 1 |
| Protection-Front Panel | IP-54 |
| Protection-Rear Panel | IP-00 |
| Weight | Approx. 1.5 Kg |

Trip Contact Rating

| | |
|------------------------------|-------------------------------------|
| Contact rating | |
| Contact relay | Dry contact Ag Ni |
| Make current | Max. 30A & carry for 1S |
| Carry capacity | 6A continuous for All contacts |
| Rated voltage | 300V AC/ 30V DC |
| DC Current Carrying Capacity | 8A@30VDC / 0.3A@110VDC/ 0.2A@220VDC |
| Breaking characteristics | |
| Breaking capacity AC | 1500VA resistive |
| | 1500VA inductive (PF=0.5) |
| | 220V AC, 6A (cos Ø ≤0.6) |
| Breaking capacity DC | 135V DC, 0.3A (L/R=30ms) |
| | 250V DC, 50W resistive or |
| | 25W inductive (L/R=40ms) |
| Operation time | <10ms |
| Durability | |
| Loaded contact | 10,000 operation minimum |
| Unloaded contact | 30,000 operation minimum |

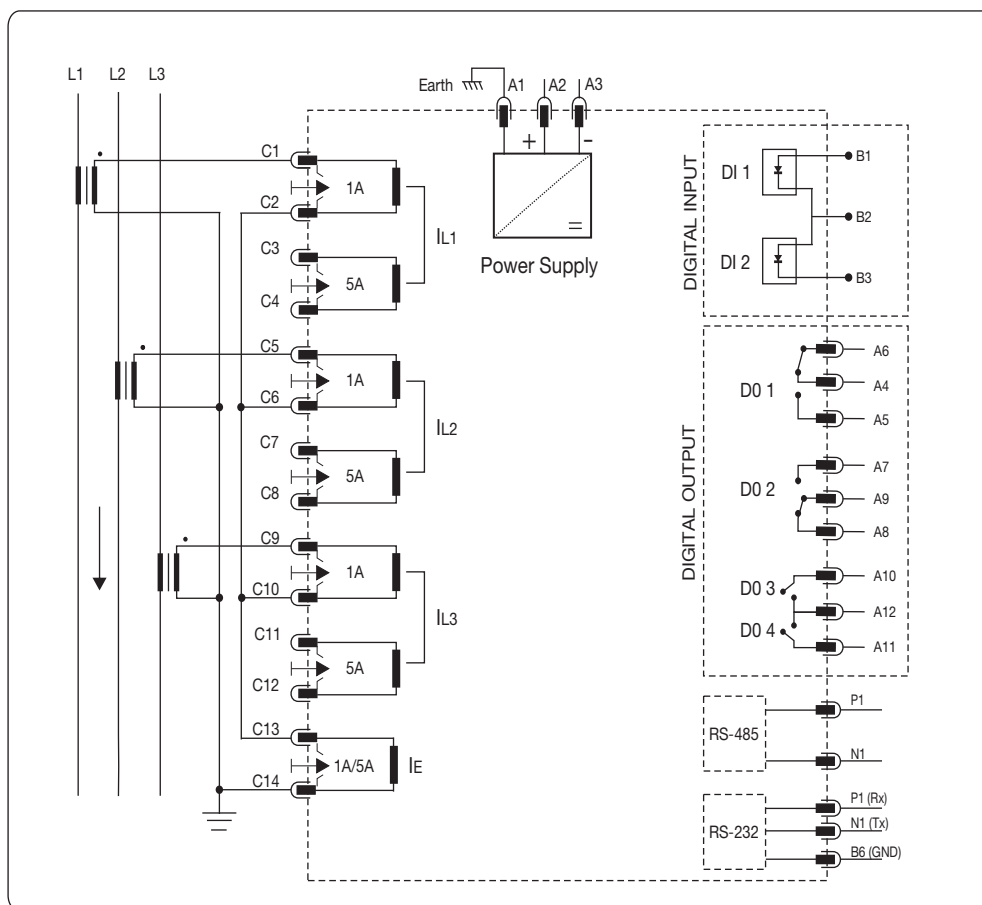
Over-voltage category : II, Insulation voltage : 300V, Pollution Degree : 2, IP 54 from Front

15) Model Selection Table

| Function | ANSI | NEX-I-100 | NEX-I-101 |
|----------------------------|---------|-----------|-----------|
| CT inputs | – | 4 | 4 |
| Over current | 50/51 | ✓ | ✓ |
| Earth fault | 50N/51N | ✓ | ✓ |
| CBFP | 50BF | ✓ | ✓ |
| Trip circuit | 74TC | x | ✓ |
| Cold Load Pickup | 62 CLD | ✓ | ✓ |
| Inrush blocking | 51H | x | ✓ |
| Digital input | – | x | 2 |
| Digital output | – | 4 | 4 |
| Fault record | – | 10 | 10 |
| Event record | – | 16 | 16 |
| Selection of 1/5A | – | ○ | ○ |
| Front communication | – | ✓ | ✓ |
| Rear comm. (RS-485/RS-232) | – | ○ | ○ |

○ : Optional based on Ordering Information

17) Connection Diagram (1A & 5A common model)

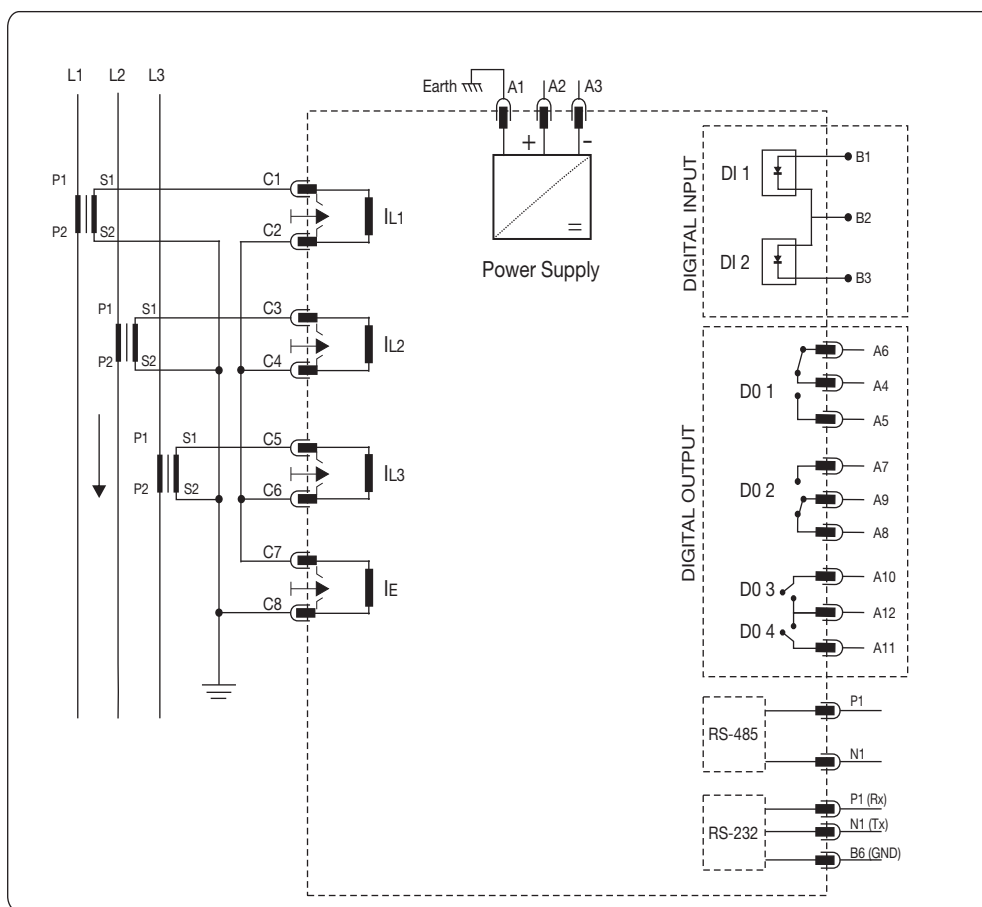


(Figure 6)

Terminal Description

| Terminal Name | Terminal Description |
|---------------|--------------------------------------------------------------------------|
| A1 | : Auxiliary Supply Earth |
| A2-A3 | : Auxiliary Supply (A2: + & A3: -) |
| P1-N1 | : For RS-485: P1(Data+ / A), N1(Data- / B) For RS-232: P1(Rx), N1(Tx) |
| B6 | : GND Terminal for RS-232 |
| A12-A11 | : Potential free Digital Output 4 |
| A12-A10 | : Potential free Digital Output 3 |
| A7-A9-A8 | : Potential free Digital Output 2 (change over) |
| A6-A4-A5 | : Potential free Digital Output 1 (change over) |
| B1-B2 | : Potential Digital Input 1 |
| B3-B2 | : Potential Digital Input 2 |
| C1-C2 | : CT Terminal for Phase current input (1A) L1 |
| C3-C4 | : CT Terminal for Phase current input (5A) L1 |
| C5-C6 | : CT Terminal for Phase current input (1A) L2 |
| C7-C8 | : CT Terminal for Phase current input (5A) L2 |
| C9-C10 | : CT Terminal for Phase current input (1A) L3 |
| C11-C12 | : CT Terminal for Phase current input (5A) L3 |
| C13-C14 | : CT Terminal for Earth current input (1A / 5A) |

Connection Diagram (1A or 5A ordering based model)

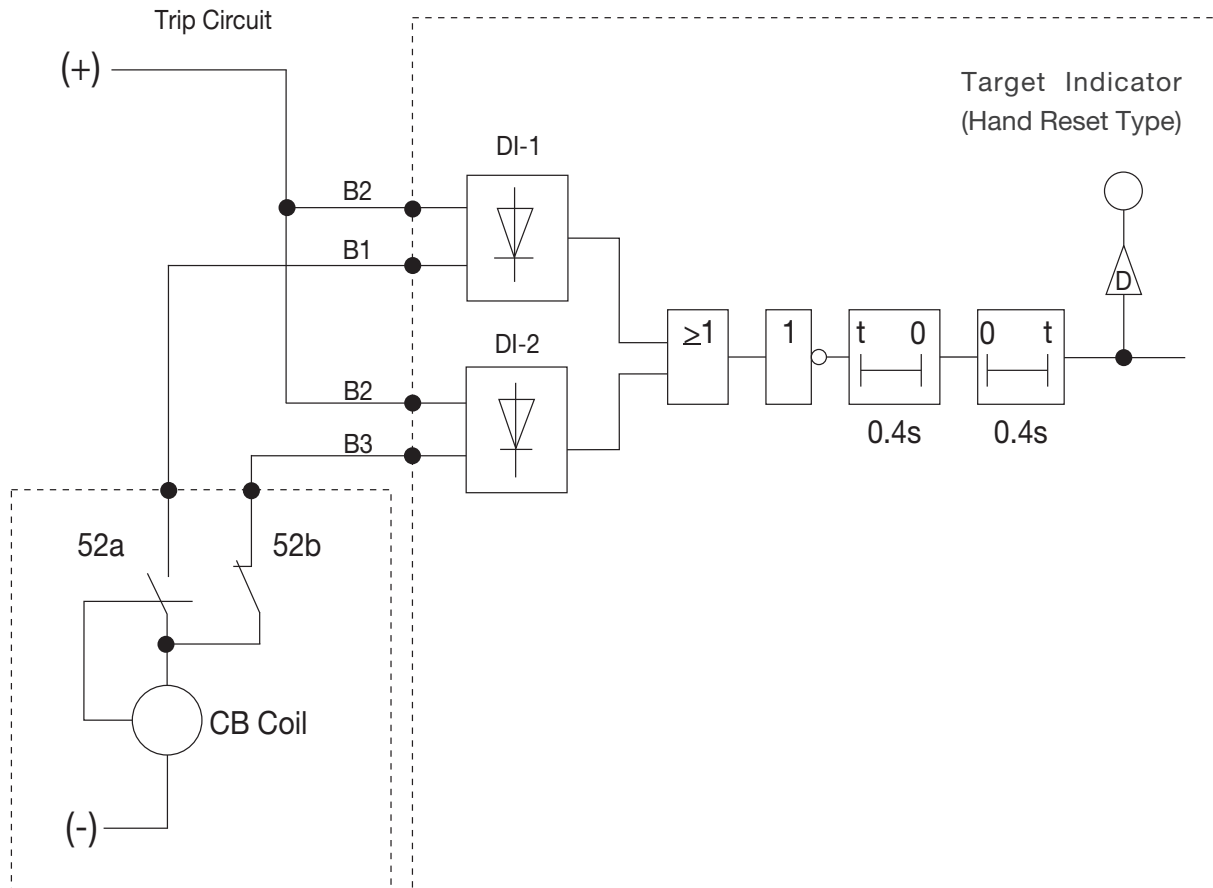


(Figure 7)

Terminal Description

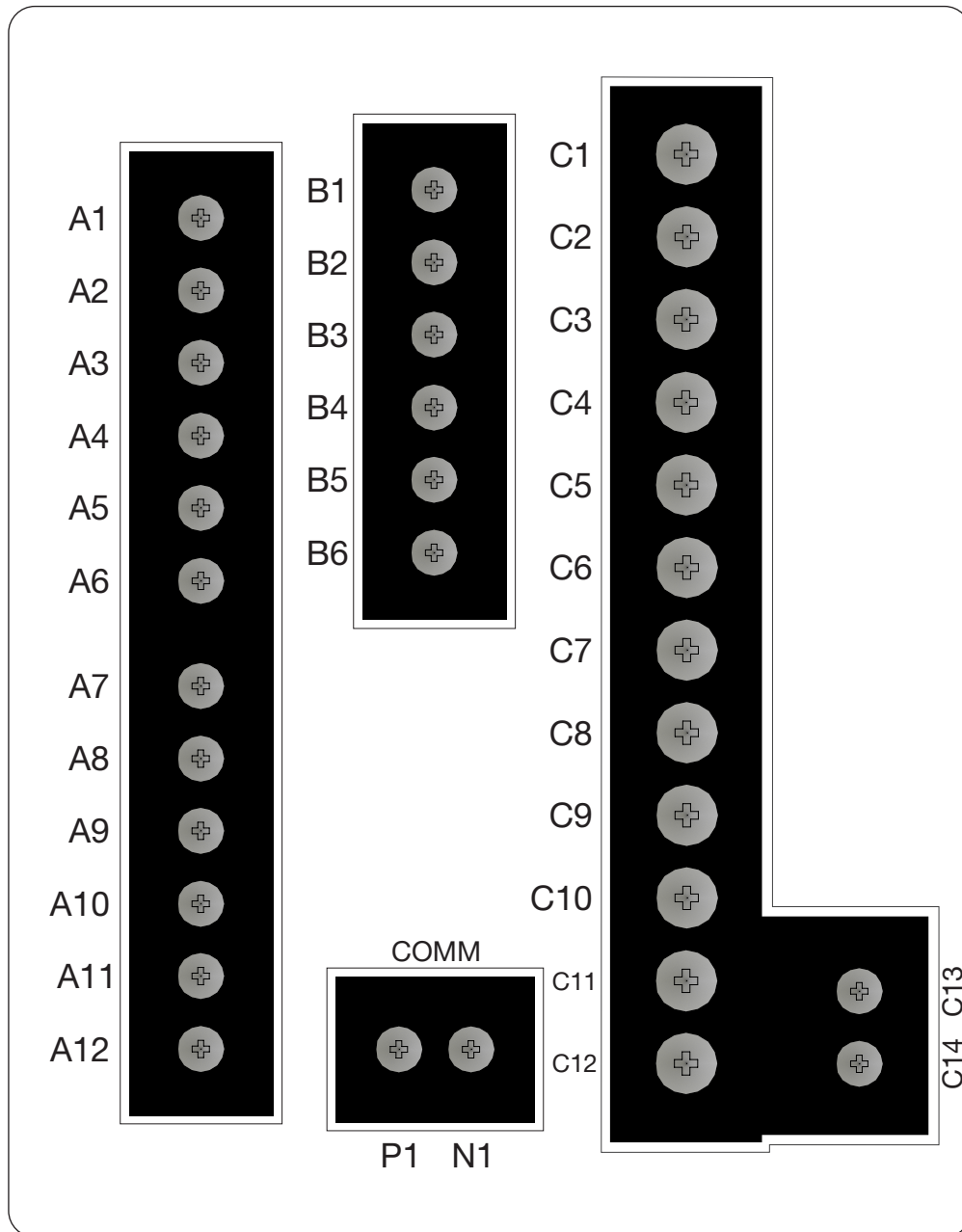
| Terminal Name | Terminal Description |
|---------------|------------------------------------------------------------------------|
| A1 | : Auxiliary Supply Earth |
| A2-A3 | : Auxiliary Supply (A2: + & A3: -) |
| P1-N1 | : For RS-485: P1(Data+ / A), N1(Data- / B) |
| | : For RS-232: P1(Rx), N1(Tx) |
| B6 | : GND Terminal for RS-232 |
| A12-A11 | : Potential free Digital Output 4 |
| A12-A10 | : Potential free Digital Output 3 |
| A7-A9-A8 | : Potential free Digital Output 2 |
| A6-A4-A5 | : Potential free Digital Output 1 |
| B1-B2 | : Potential Digital Input 1 |
| B3-B2 | : Potential Digital Input 2 |
| C1-C6 | : CT Terminal for Phase current inputs L1(C1-C2), L2(C3-C4), L3(C5-C6) |
| C7-C8 | : CT Terminal for Earth current input |

16) Trip Circuit Supervision Diagram



(Figure 5) (Trip Circuit Supervision Function)

18) Back Terminal Diagram

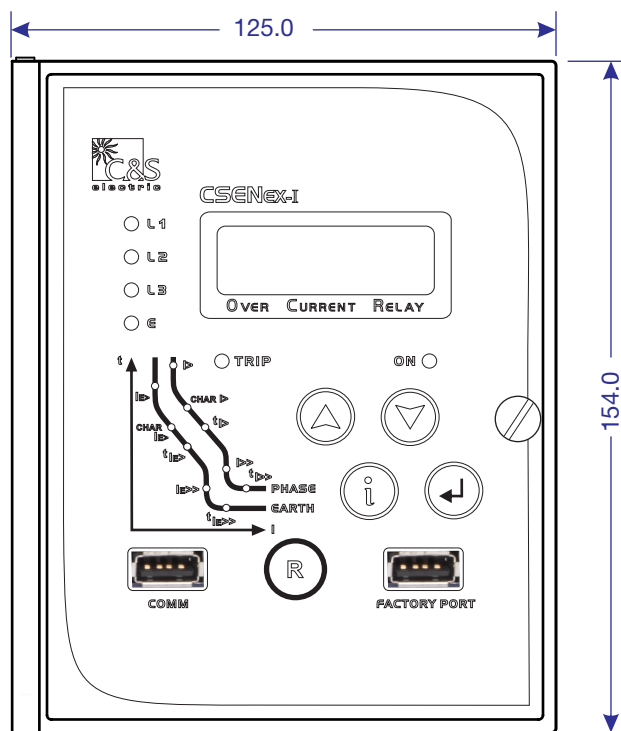


(Figure 8)

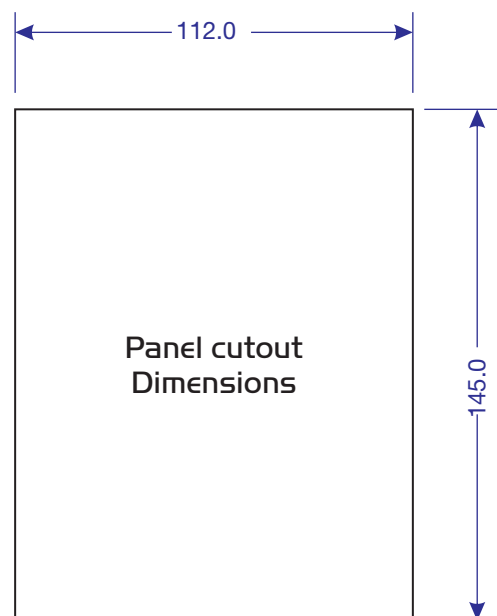
19) Dimensional Details

(All the dim. are in mm, Gen. Tol.: $\pm 1.0\text{mm}$)

Front View

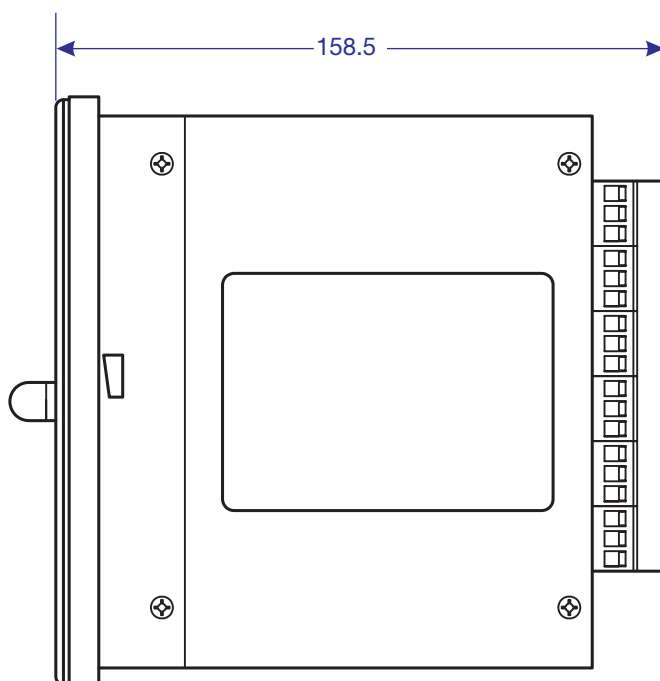


(Figure 9)



(Figure 10)

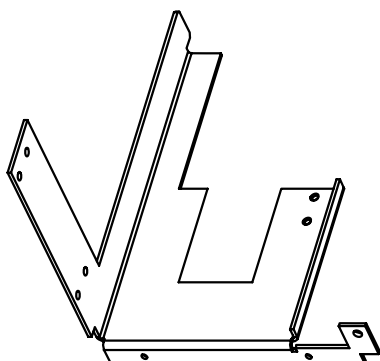
Side View



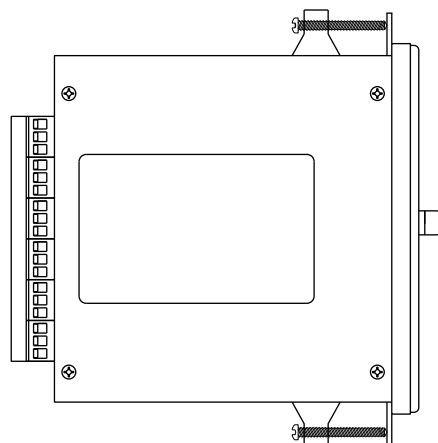
(Figure 11)

20) Relay Mounting CSENex-I relay is mounted on “L” bracket as shown in below drawing:

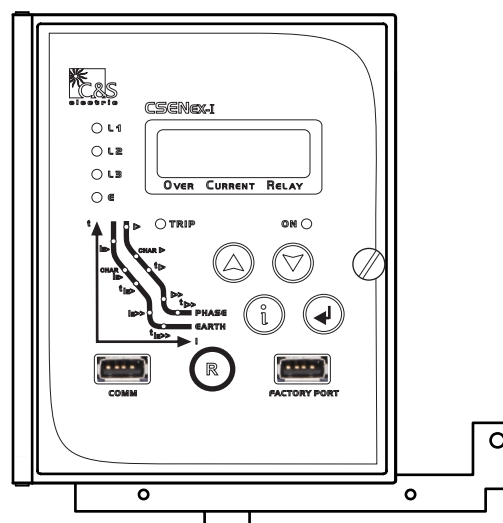
Isometric view of
Mounting Bracket



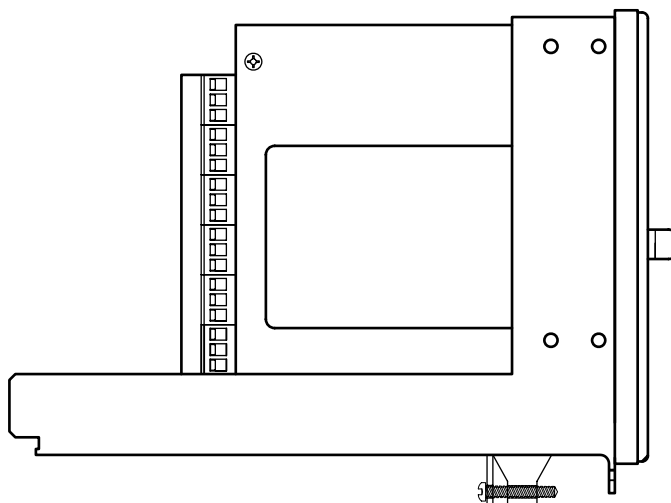
Mounting arrangement
using clamps



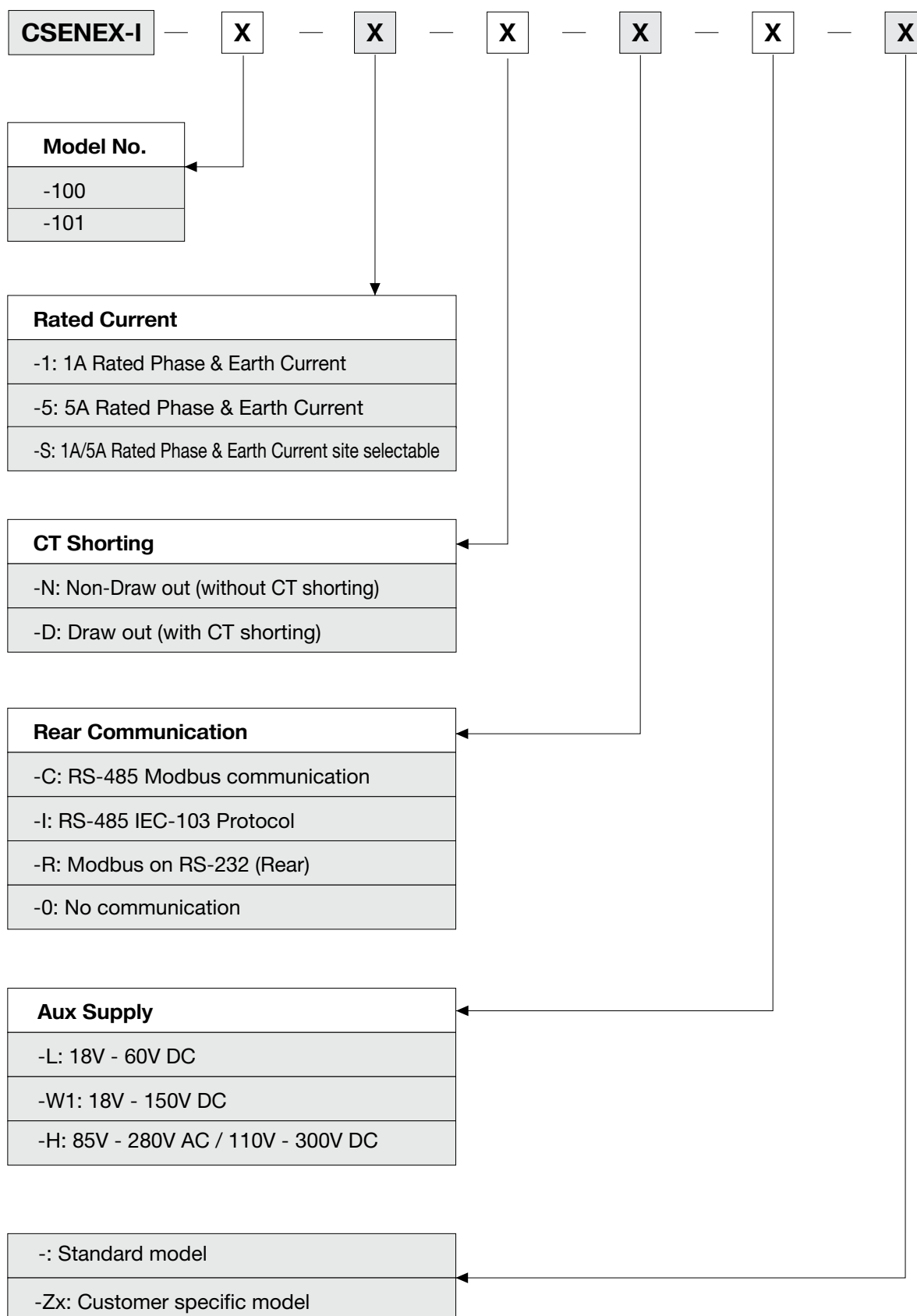
Front view of Relay
with Mounting Bracket



Side view of Relay with
Mounting Bracket



21) Ordering Information



EXAMPLE: CSENEX-I-100-1-N-C-L-Zx

[illegible]

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Branch Address

| Branch | Phone | Fax | E-mail |
|--------------|-------------------------------|------------------|------------------------------|
| Ahmedabad: | +91-79-615651 22/23/24 | +91-79-61565130 | ahmedabad@cselectric.co.in |
| Bangalore: | +91-80-305703 72/73, 30570347 | +91 2558 4839 | bangalore@cselectric.co.in |
| Bhubaneswar: | +91-674-2507265 | +91 674 2507265 | bhubaneswar@cselectric.co.in |
| Chennai: | +91-44-33534501,33534521-23 | ---- | chennai@cselectric.co.in |
| Cochin: | +91-484-3071717 | +91 0484 3071716 | cochin@cselectric.co.in |
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| Hyderabad: | +91-40-485340 80/82 | ---- | hyderabad@cselectric.co.in |
| Kolkata: | +91-33-392121 19-21 | ---- | ---- |
| Mumbai: | +91-22-241147 27/28 | ---- | cspc.mumbai@cselectric.co.in |
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